

CV800 Series Multi-Function Inverter

Shenzhen Canroon Electrical Appliances Co., Ltd

Product Overview



CV800 series multi-function inverter is specially designed for small and medium power equipment.

The product adopts vectorized V/f control technology, built-in PID control, multi-speed control, programmable operation control, standard Modbus communication and other technologies. The compact structure can further reduce the installation space.

Product Features

- Compact and powerful
- High starting torque, adapt to various loads
- Supports programmable operation control, making complex applications easier
- Stronger overload capacity, shorter acceleration time
- Built-in PID function for full-closed-loop control
- Comprehensive protection function, more reliable operation

CV800 series application field

CV800 series multi-function inverter is powerful functions and excellent in performance, suitable for medium and small power applications, such as constant pressure water supply, woodworking machinery,textile equipment, food filling, logistics equipment, automated production lines, ceramic equipment, electronic equipment, packaging machinery, etc.



Constant pressure water supply



Food filling



Textile equipment



Packaging machinery



Automated production line



Ceramic equipment

Inverter model description



Overall dimensions

Voltage class	Specification model	Rated Power (KW)	Dimensions (mm)			Installation size (mm)			Package dimensions (mm)			Net weight	Figure
			W1	H1	D	W2	H2	φ	L	М	Н	(kg)	5
380V 3-phase	CV800-00AG-14TF	0.4KW	95.5	158.5	132.5	83.5	145	5	195	132	172	1.25	A
	CV800-00BG-14TF	0.75KW											
	CV800-001G-14TF	1.5KW											
	CV800-002G-14TF	2.2KW											
	CV800-004G-14TF	3.7KW											
	CV800-005G-14TF	5.5KW		240	178.5	129	228.75	5.3	300	210	250	2.2	В
	CV800-007G-14TF	7.5KW	140										
	CV800-011G-14TF	11 KW											



Technical Index and Specification

ľ	Rated Voltage, Frequency		3-phase (-4T) 380V;50/60HZ							
put	Allowed Voltage Range		3-phase (-4T)320V~460V							
Output	Voltage		4T; 0~380V							
	Fi	requency	0~600HZ	0~600HZ						
	Overl	erload Capacity 10% for long-term, 15			% for 1 min, 180% for 5s					
С	Contro	l Mode	V/F control. Simple vector control							
	Frequency Setting		Analog Input		0.1% of maximum output frequency					
Control Character	R	esolution	Digital Setting		0.1Hz					
	Frequency Precision		Analog Input		Within 0.2% of maximum output frequency					
			Digital Set	ting	Within 0.01% of set output frequency					
			V/F Curve (voltage frequency character)		Reference frequency setting 5~600 Hz, multipoint V/F curve setting, or fixed curve of constant torque, low decreasing torque 1, low decreasing torque 2, square torque					
	V/	/F Control	Torque Compensation		Manual setting: 0.0~30% of rated output					
			Automatic Current-limiting and Voltage-limiting		During acceleration, deceleration or steady running, detect automatically the current and voltage of motor stator, and control it within bounds based on unique algorithm, minimize fault-trip chance					
			Voltage Frequency		Adjust pressure/frequency ratio according to motor parameter and unique algorithm					
	Se	enseless stor Control	Torque Character		Starting torque;100% rated torque at 5.0 Hz (V/F Control) 150% rated torque at 1.5 Hz (simple vector control)					
	100		Current and		Current closed-loop control. free from current impact, perfect restrain function of overcurrent and overvoltage					
	Undervoltage Restrain during Running		Specially for users with a I maintain the longest possi		low or unsteady voltage power grid: even lower than the allowable voltage range, the system can ible operating time based on its unique algorithm and residual energy allocation strategy					
Typical function	Multi-velocity and Traverse Operation		7-segment programmable multi-velocity control, multiple operating modes are optional.							
	PID Control		Built-in PID controller (able to preset frequency).							
	RS485 Communication		Standard configuration RS485 communication function, multiple communication protocol for choice, synchronizing control function.							
	Frequency Setting		Analog Input	Analog Input Direct voltage 0~10V, direct current 0~20mA (optional up limit and lower limit)						
		, ,	Digital Output	Digital Output Operation panel setting, RS485 port setting, UP/DW terminal control, or combined with analog input						
	Ou	tout Signal	Digital Output	1 chann	el OC output and one channel relay output (IA, IB,IC), up to 14 choices					
			Analog Input	physical	inel analog signal output, output ranging within U~2UMA or U~1UV with flexibly setting, achievable output of al quantities like set frequency, output frequency					
	Automatic Steady -voltage Operation		Dynamic steady state, static steady state, and unsteady voltage for choices to obtain the steadiest operation							
	Acceleration and Deceleration Time Setting		0.1S~999.9min continuous setting							
	Dynamic Braking		Dynamic braking initial voltage, backlash voltage and dynamic braking continuous adjustable							
	DC Braking		Halt DC braking initial frequency:0.00~(F0.05)upper limit frequency Braking time:0.0~30.0s;Braking current:0.0%~50.0%of rated current							
	Low Noise Running		Carrier frequency 1.0kHz~16.0kHz continuous adjustable, minimize motor noise							
		Counter	A built-in counter, facilitate system integration							
	Operation Function		RS485 communication, frequency setting, nequency hopping operation, reversal fulning resident, sin nequency compensation, RS485 communication, frequency control of progressive increase and decrease, failure recovery automatically, etc.							
Display	Operation	n State	Output frequency, output current, output voltage, motor speed, set frequency, m		current, output voltage, motor speed, set frequency, module temperature, PID setting, feedback, analog input and output.					
	Display	Alarm	The latest 1 faults record; running parameters record when the latest fault tripping happens including output frequency, set frequency current, output voltage, DC voltage and module temperature etc 6 running parameters record.							
Prot	tective	e Function	Overcurrent, ov parameter adju	vercurrent, overvoltage, undervoltage, module fault, electric thermal relay, overheat, short circuit, default phase of input and output, motor arameter adjustment abnormality, internal memory fault, etc.						
Environme	Ambient Temperature		-10 C ~+40 C (please run the VFD in derated capacity when ambient temperature is 40°C~50°C))							
	Ambient Humidity		5% ~ 95%RH, without condensing drops							
	Surroundings		Indoors (without direct sunlight, corrosive or flammable gas, oil fog and dust)							
ent	Altitude		Running in derated capacity above 1000m, derate 10% for every 1000m rise.							
	Prot	ection Level	IP20							
ure	Cooling Method		Air cooling with fan control							
Inst	tallatic	on Method	Wall-hanging type, Cabinet type							

Basic Running Wiring

The wiring parts of VFD include major loop and control loop. Open the cover of I/O terminals, users can see the major loop terminal and control loop terminal, and must conduct the wiring according to the following diagram.



0.4kw ~ 11 kw

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